

# CAN and Multiplexing



## CAN and Multiplexing



- **Summarize CAN multiplexing history & origins**
- **Explain CAN technology**
- **Explain CAN benefits**



- **CAN stands for Controller Area Network**
- **Definition: Serial bus communication for real-time control application.**

# What do we mean by CAN?



- **CAN is a communication across a pair of wires to different nodes/microprocessors**
- **Messages on the CAN bus do not carry addresses, only identifiers**
- **Every node sees every message on the CAN bus**
- **CAN is a differential signal on two wires**

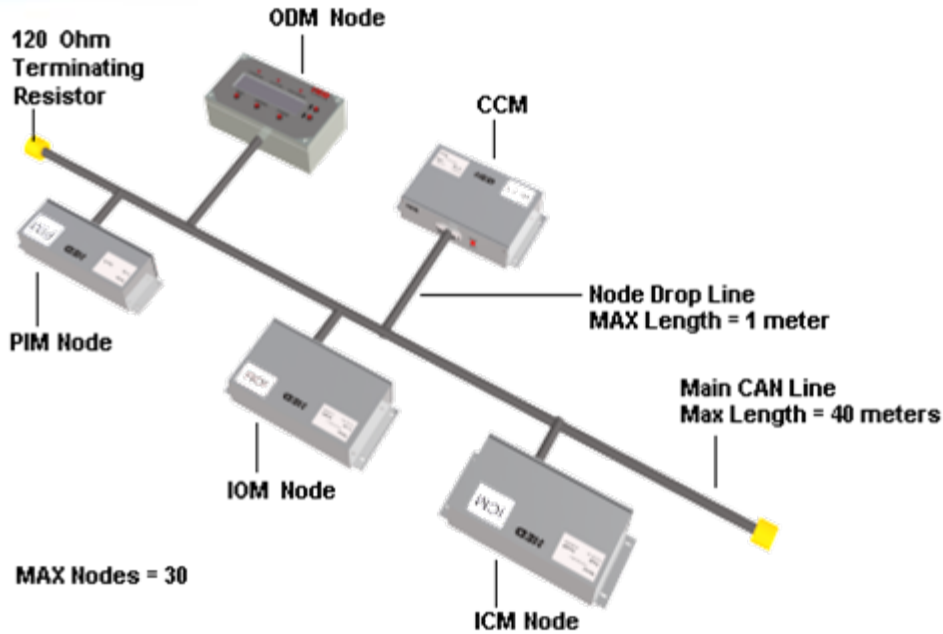


- **CAN (Controller Area Network) was created by Robert Bosch GmbH in mid 1980's**
- **Version 1.2 had 11 bit identifiers**
- **Version 2.0B released Sept. 1991 provided for 11 bit and 29 bit identifiers**
- **Base patent still held by Bosch**



- **1983 Developed by Bosch**
- **1987 First CAN chips by Intel & Philips**
- **1992 CAN is introduced to automation**
- **1992 First car with CAN (Mercedes Benz)**
- **1994 SAE J1939 released**
- **1995 ISO 11898 is released**

# CAN System





## General Applications

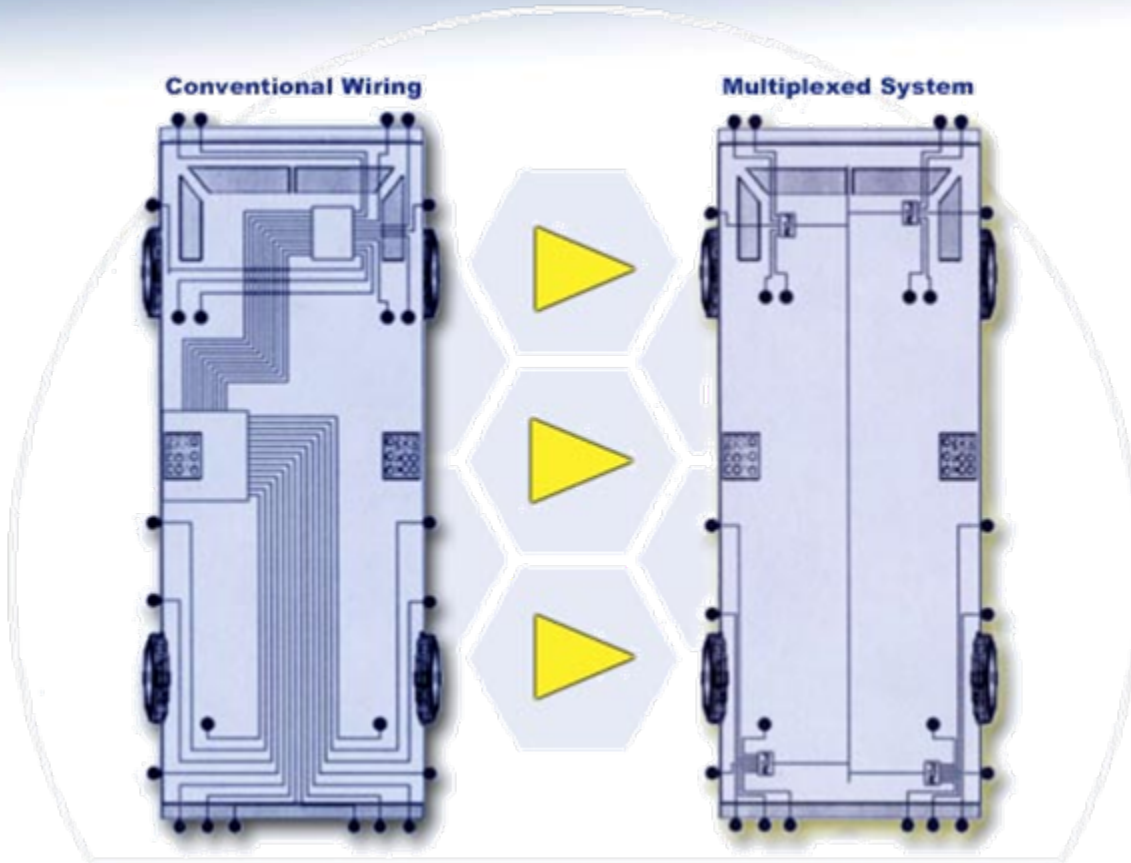
- Cars
- Packaging equipment
- Medical systems
- Photo copiers
- Marine controls and navigation systems
- Elevator controls

## ■ HED examples

- Military vehicles
- Agriculture machinery
- Construction equipment
- On and off highway equipment



# CAN application

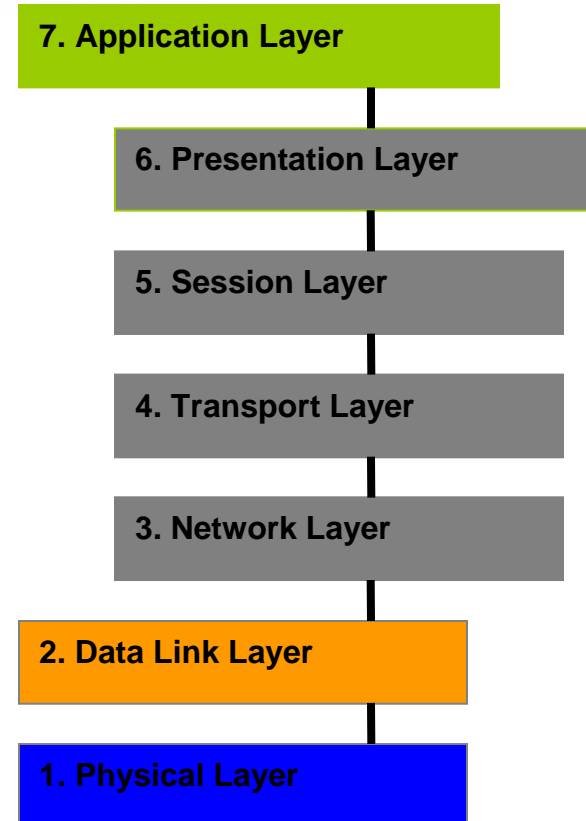




- **Communication rate is 250Kbits/second-  
J1939**
  - CAN max is 2Mbits/second
- **11 or 29 bit identifier**
  - CANOpen is only 11 bit identifier
  - CAN 2.0 is backward compatible
- **120 ohm terminating resistors**



- **We are interested:**
  - Physical
  - Data Link
  - Application
- **All the layers together make up the OSI (open system interconnect)**



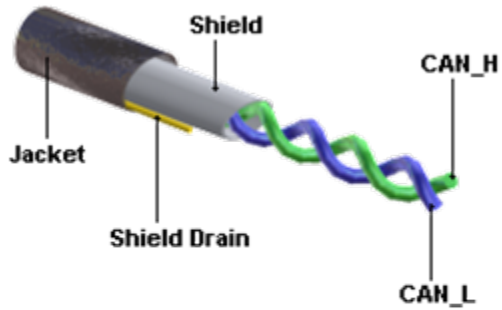
# CAN standardization



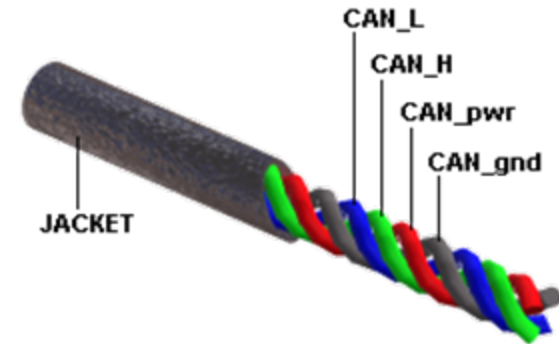
Application Profile				CANopen application profiles	SAE J1939-based application profiles	
Device Profile			DeviceNet device profiles	CANopen device profiles		
Application Layer		SDS EN 50325-3	DeviceNet EN 50325-2	CANopen EN 50325-4		
Data Link Layer	ISO 11898-1 (11-bit ID)			ISO 11898-1 (11-bit <i>and</i> 29-bit ID)		ISO 11898-1 (29-bit ID)
Physical Layer	ISO 11898-2					ISO 11898-2



- **Consist of the hardware needed to communicate from node to node**
  - **Physical/driver chip**
    - **Converts 1's & 0's to differential voltage**
  - **Twisted pair of wire**
  - **Connectors**

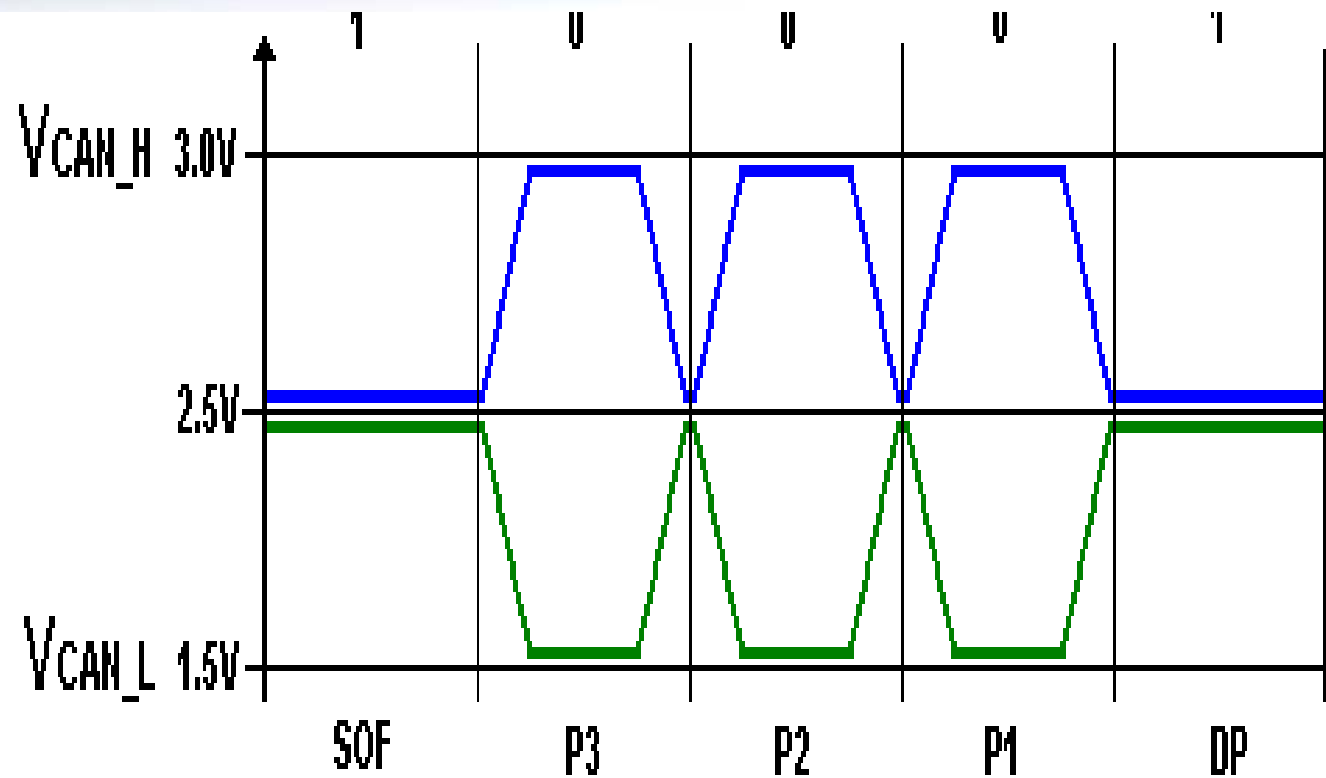


**2 Conductor**



**4 Conductor**

# CAN Signal





- **The layer that defines data, remote, error, and overload frames.**
- **Layer that turns the data into raw bits**
- **Also part of the error detection**





## ■ Bit Monitoring

- Any node automatically monitors and compares the actual bit level on the bus with the level that it transmitted. If the two are not the same, a bit error is flagged.

## ■ Stuff Error

- If five consecutive identical bit levels have been transmitted, the transmitter will automatically inject (stuff) a bit of opposite polarity into the bit stream. The receive node will automatically de-stuff.



- **Cyclic Redundancy Check Field (CRC)**
  - Every message transmitted contains a 15 bit CRC code. If the receivers calculate a different CRC, a error flag is raised.
- **Form Error**
  - Violation of fixed format Bit fields
- **Acknowledge Error (ACK)**
  - If a node determines a message has not been ACKnowledged then the ACK error is flagged.



- **The application layer is the communication layer of the OSI.**
  - **Performs common end user services**
  - **HED application code**



- **J1939**
  - Diesel engines, busses, fire trucks, cranes, etc...
- **CAN Kingdom**
- **CANOpen**
  - Used in Europe especially Germany
- **DeviceNet**
  - Used in USA and Asia for PLC controllers
- **Proprietary**
  - HED

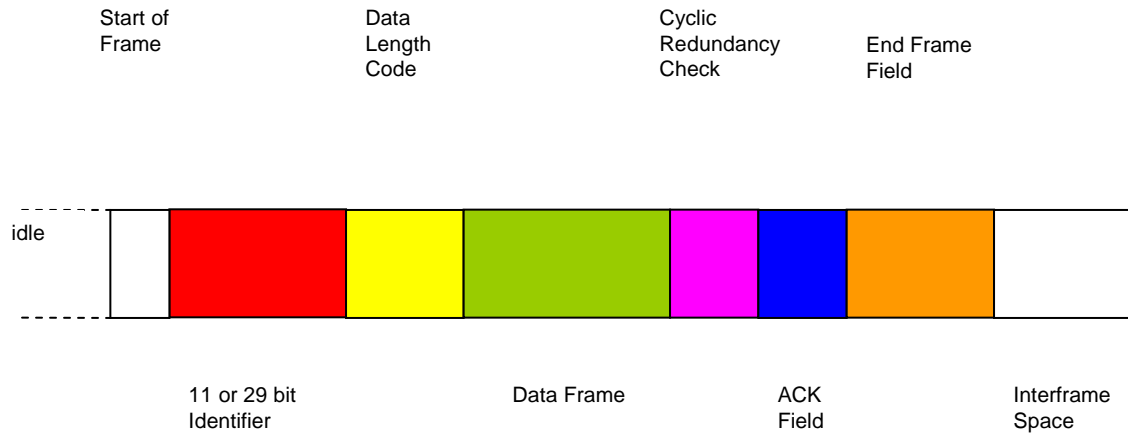


- ◆ 1991: CAN Kingdom
- ◆ 1992: **CAN Application Layer (CiA 20X series)**
- ◆ 1994: Smart Distributed System (IEC 62026, EN 50325)
- ◆ 1994: DeviceNet (IEC 62026, EN 50325)
- ◆ 1994: Truck and bus (SAE J1939, ISO 11898)
- ◆ 1995: **CANopen (CiA 301, EN 50325)**
- ◆ 1997: OSEK-COM/NM (ISO 17356 series)
- ◆ 1999: Truck/trailer (ISO 11992-1/-2/-3)
- ◆ 2001: Diagnostics on CAN (ISO 15765)
- ◆ 2002: ISOBUS (ISO 11783 series)
- ◆ 2006: **Re-creation vehicle CAN (CiA 501/2)**



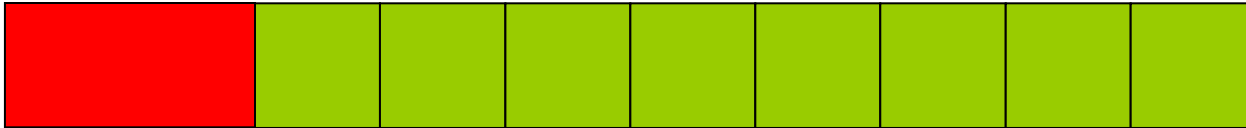


## Full CAN message scheme:





## What we are interested in:



11 or 29 bit  
Identifier

0-8 bytes Data Frame

# Example J1939 Message



Program Group Number (pgn) 65262 – **Engine Temperature 1 – ET1**

**Transmission rate:** 1 sec  
**Data Length:** 8 bytes  
**Data Page:** 0  
**PDU Format:** 254  
**PDU Specific:** 238  
**Default Priority:** 6  
**Parameter Group Number:** 65262 (00FEEE hex)

Bit Start Position	Bytes Length	Suspect Parameter Number SPN Description	SPN
1	1 byte	<b>Engine Coolant Temperature</b>	<b>110</b>
2	1 byte	<b>Fuel Temperature</b>	<b>174</b>
3-4	2 bytes	<b>Engine Oil Temperature 1</b>	<b>175</b>
5-6	2 bytes	<b>Turbo Oil Temperature</b>	<b>176</b>
7	1 byte	<b>Engine Intercooler Temperature</b>	<b>52</b>
8	1 byte	<b>Engine Intercooler Thermostat Opening</b>	<b>1134</b>



# Example J1939 Message



- Suspect Parameter Number 175 – **Engine Oil Temperature 1**
- **Data Length:** 2 bytes
- **Resolution:** 0.03125 deg C/bit, -273 deg C offset
- **Data Range:** -273 to 1735 deg C
- **Type:** Measured
- **Suspect Parameter Number:** 175
- **Parameter Group Number:** [65262]

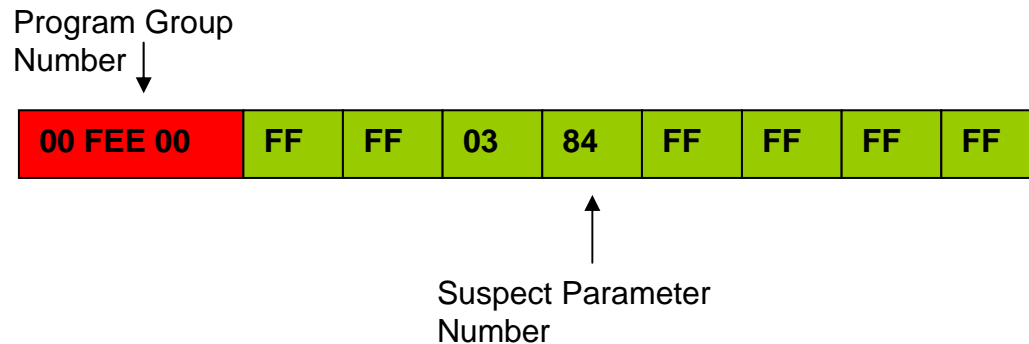
Program Group  
Number ↓



↑  
Suspect Parameter  
Number



**As the engine oil temperature changes, then bytes 3 & 4 change to show the value in HEX.**





- **SAE (Society of Automobile Engineers)**
- **CiA (CAN in Automation)**
- **ODVA (DeviceNet)**

# Why do we use CAN?



- **Industry proven**
- **Bit collision detection and handling**
- **Cost saving**
- **Diagnostics for multiple module systems**
- **EMI/RFI**



- **Check these websites for more information**
  - [www.sae.org](http://www.sae.org)
  - [www.can-cia.org](http://www.can-cia.org)
  - [www.hedonline.com](http://www.hedonline.com)
  
- **HED papers**
  - **Large Scale Applications of J-1939 CAN**



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